

How to Code Geometry

Writing Subroutine HOWFAR

**Walter R. Nelson
Stanford Linear Accelerator Center**



Introduction

- An EGS User Code requires
 - SUBROUTINE AUSGAB for scoring results of interest
 - SUBROUTINE HOWFAR to provide information about the nature of the geometry

- The most trivial HOWFAR is a *homogeneous, infinite* medium

```
SUBROUTINE HOWFAR;  
RETURN;  
END;
```

- In this lecture we will show you how to write code that can be used for more complicated geometries

Useful Geometry References

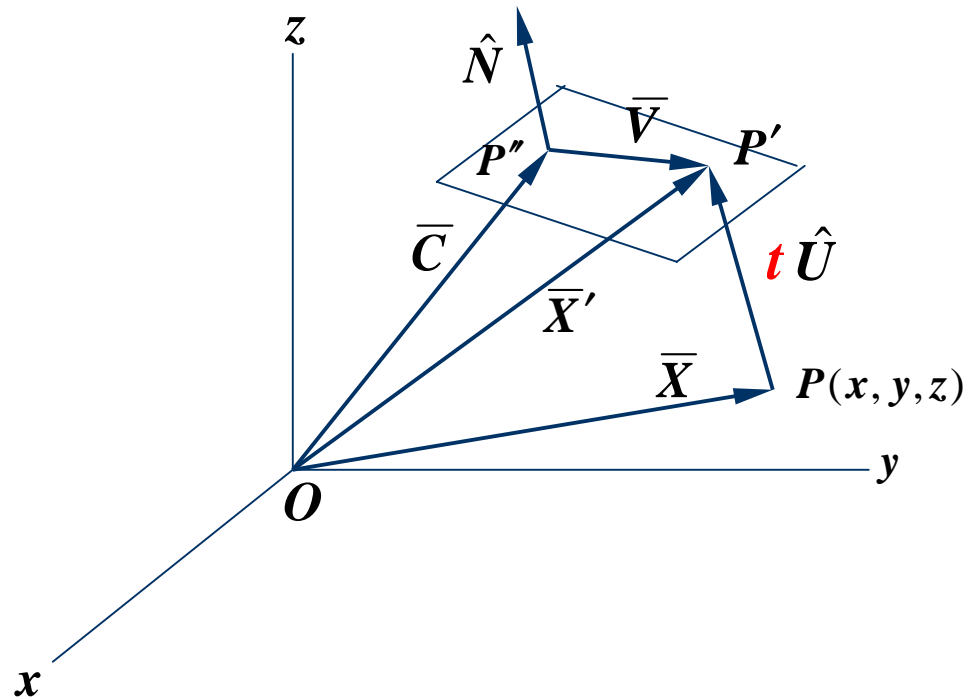
- W. R. Nelson and T. M. Jenkins, “Writing SUBROUTINE HOWFAR for EGS4”, SLAC-TN-87-4 (31 August 1988/Rev.)
- W. R. Nelson and T. M. Jenkins, “Geometry Methods and Packages”, Chapter 17 in *MORTE CARLO TRANSPORT OF ELECTRONS AND PHOTONS* (Plenum Press, 1988)

Note: In this lecture, the word “**EGS**” applies to both EGS4 and EGSnrc

Items Covered in this Lecture

- General mathematical considerations (vectors)
- The role of key variables in EGS
- Special subprograms available with EGS
- Mortran3 *macro-equivalent* forms of these subprograms
- Putting all the modules together to form the geometry
- Other geometry packages—e.g., Combinatorial Geometry

Mathematical Considerations



- Particle trajectories are described by the position and direction vectors

$$\bar{X} = x\hat{i} + y\hat{j} + z\hat{k} \quad \text{and} \quad \hat{U} = u\hat{i} + v\hat{j} + w\hat{k}$$

represented by $X(NP)$, $Y(NP)$, $Z(NP)$ and $U(NP)$, $V(NP)$, $W(NP)$, respectively, and are passed in **COMMON/STACK/** along with the stack pointer, NP

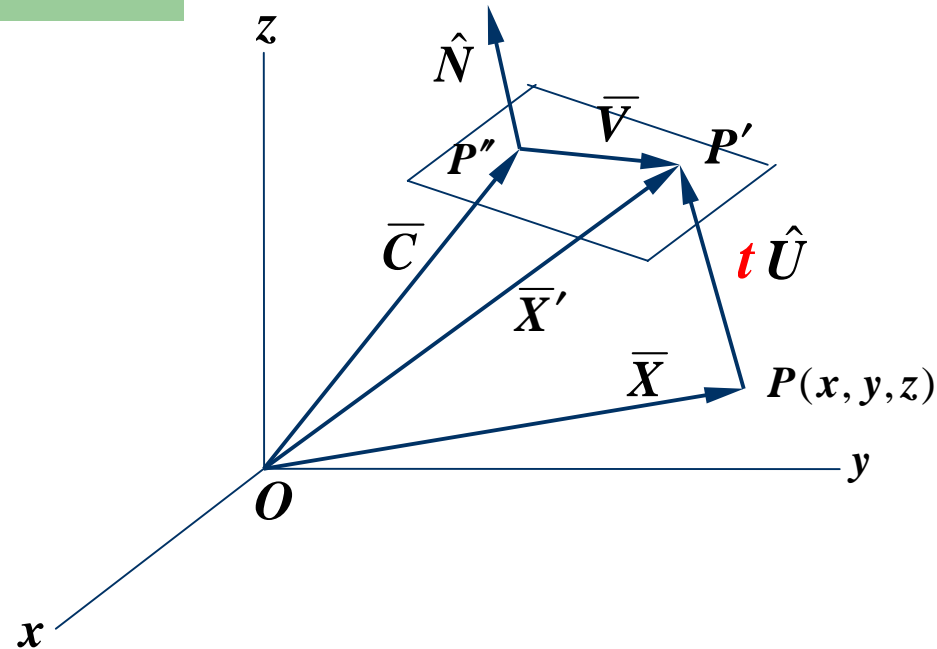
Subroutine HOWFAR

...Math Considerations (cont.)

- The quantities $\bar{\mathbf{X}}(\mathbf{x}, \mathbf{y}, \mathbf{z})$ and $\hat{\mathbf{U}}(\mathbf{u}, \mathbf{v}, \mathbf{w})$, together with such things as particle **type**, **energy**, **weight**, *time*, etc., define the state function of the particle (and are called *stack variables*)
- In writing SUBROUTINE HOWFAR, the problem becomes one of
 - determining the point of intersection, P' , of the particle trajectory with any given surface,
 - which allows for the extraction the distance t ,
 - and comparing t with **USTEP**—the transport step about to be taken for the current particle being followed

Referring to the figure again...

...Math Considerations (cont.)

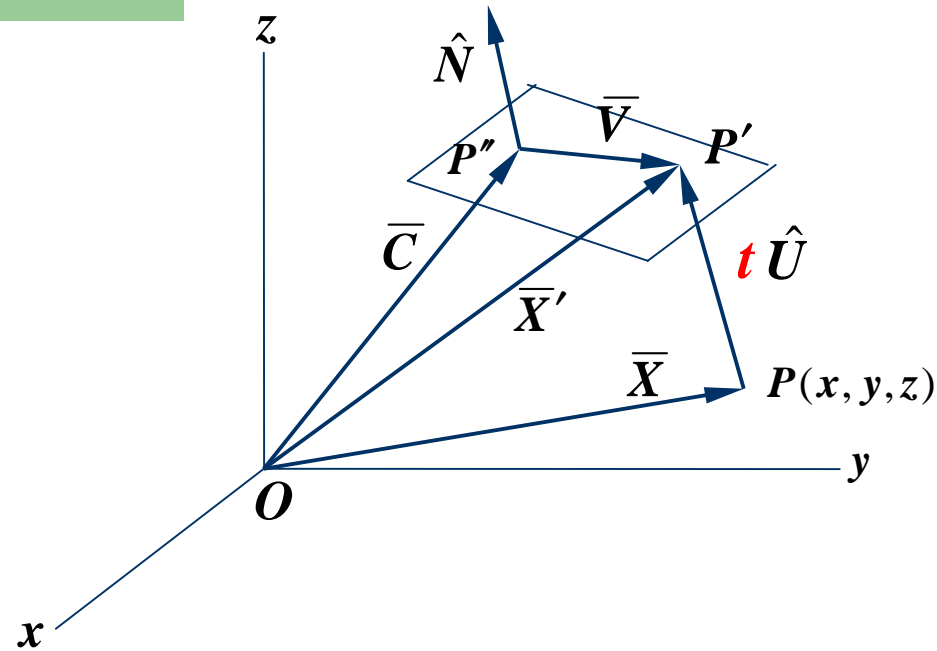


- A plane surface can be described by the vector to a point, P'' , on the surface and a unit vector normal to it,

$$\bar{C} = c_1 \hat{i} + c_2 \hat{j} + c_3 \hat{k} \quad \text{and} \quad \hat{N} = n_1 \hat{i} + n_2 \hat{j} + n_3 \hat{k}$$

which are the arrays **PCOORD(3:100)** and **PNORM(3:100)**, respectively, that are passed in **COMMON/PLADTA/** .

...Math Considerations (cont.)



- The condition for the intersection point (P') to *lie on the plane* is obtained from the vector dot product $\bar{V} \cdot \hat{N} = 0$.
- From the diagram we see that

$$\bar{V} = \bar{X}' - \bar{C} = \bar{X} + t\hat{U} - \bar{C} ,$$

which leads to the equation...

...Math Considerations (cont.)

$$t = \frac{(\bar{C} - \bar{X}) \cdot \hat{N}}{\hat{U} \cdot \hat{N}} = \frac{(c_1 - x)n_1 + (c_2 - y)n_2 + (c_3 - z)n_3}{un_1 + vn_2 + wn_3}$$

- The following physical situations apply
 - a) $t > 0$: particle travels away from the plane
 - b) $t < 0$: particle travels towards the plane
- Note: The above equation is indeterminate when the denominator is 0, corresponding to the physical situation in which the particle travels parallel to the plane

The PLANE1 Algorithm

```

SUBROUTINE PLANE1(IPLN,INPT,IHIT,TPLN);
  "-----"
  "  Input:  IPLN      Plane identification number                "
  "          INPT = 1  Surface normal points AWAY from current region  "
  "          = -1    Surface normal points TOWARDS current region    "
  "  Output: IHIT = 0  Particle travels AWAY from surface (a miss)    "
  "          = 1     Particle travels TOWARDS surface (a hit)        "
  "          = 2     Particle travels PARALLEL TO surface (a miss)   "
  "          TPLN     Distance to surface (when IHIT=1)              "
  "-----"
  COMMON/STACK/E(40),X(40),Y(40),Z(40),U(40),V(40),W(40),DNEAR(40),
        WT(40),IQ(40),IR(40),NP;
  DOUBLE PRECISION E;
  COMMON/PLADTA/PCOORD(3,100),PNORM(3,100);

  UDOTN=PNORM(1,IPLN)*U(NP) + PNORM(2,IPLN)*V(NP) + PNORM(3,IPLN)*W(NP);
  UDOTNP=UDOTN*INPT;

  IF (UDOTNP.EQ.0.0) [ IHIT=2; "Parallel to z-axis (indeterminant)" ]
  ELSEIF (UDOTNP.LT.0.0) [ IHIT=0; "Traveling away from surface" ]
  ELSE [ "Traveling towards surface---determine distance (TPLN)"
        IHIT=1;
        TPLN=PNORM(1,IPLN)*(PCOORD(1,IPLN)-X(NP))
              + PNORM(2,IPLN)*(PCOORD(2,IPLN)-Y(NP))
              + PNORM(3,IPLN)*(PCOORD(3,IPLN)-Z(NP));
        TPLN=TPLN/UDOTN;
        ]
  RETURN;
  END;

```

Except for parameter **INPT**, which allows for more efficient determination of *t*, algorithm above is based precisely on the previous equation

Subroutine HOWFAR

Specifications for HOWFAR

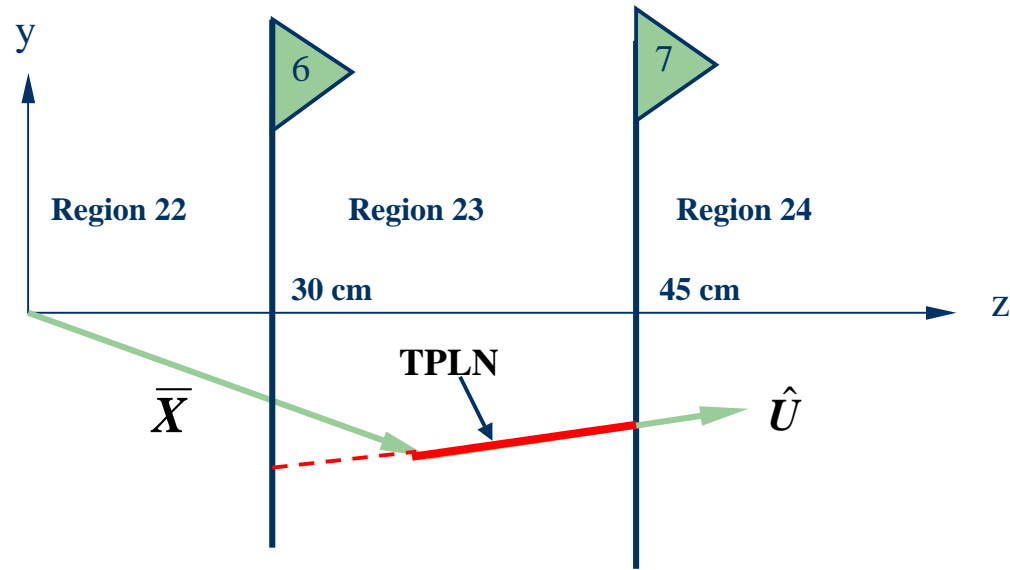
- For every **CALL SHOWER** invocation in the MAIN program of the User Code, particles that are being transported are placed on a *stack*
- The *current* particle being tracked is identified on the *stack* by the pointer, **NP**
- There are three EGS variables that play an important role in HOWFAR: **USTEP**, **IDISC**, and **IRNEW**
- These variables are passed in **COMMON/EPCONT/**

...Specifications for HOWFAR (cont.)

- On entry to HOWFAR, EGS has predetermined that it would like to transport the current particle by a straight-line distance, **USTEP**
- HOWFAR must then determine if **USTEP** will carry the particle past the boundary towards which it is heading
- If it does carry it past, HOWFAR must do two things:
 - Shrink **USTEP** to the distance to the boundary, **t**
 - Set **IRNEW** to the “new” region in which the particle is expected to end up
- Otherwise, a **RETURN** is simply made to the subroutine that called HOWFAR (i.e., ELECTR or PHOTON)

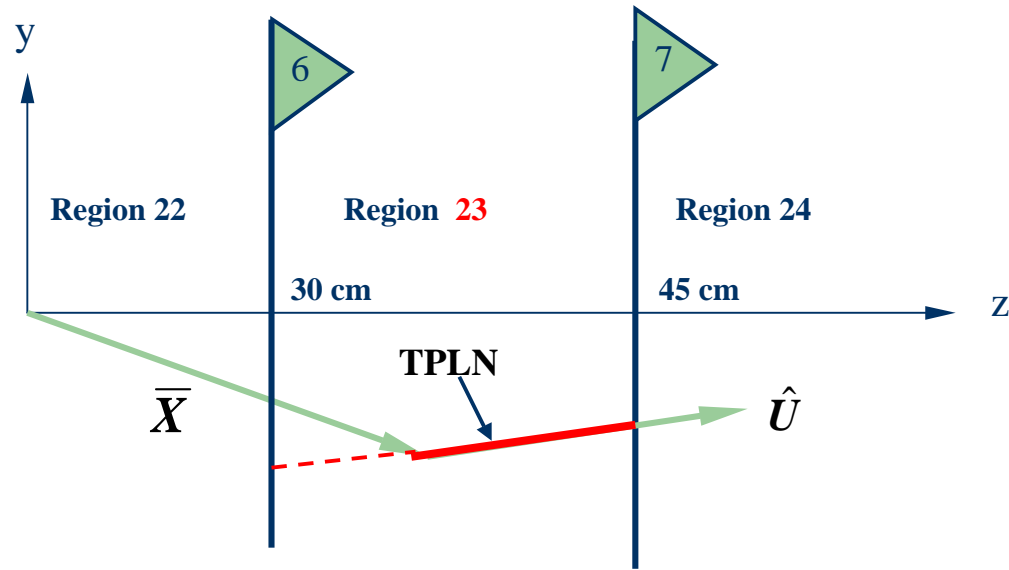
- On occasion a particle will end up in a region designated by the user as a *discard region*
- In such cases, the flag **IDISC** is set equal to **unity** in HOWFAR and a **RETURN** is made to the calling subprogram
- The distance to the next boundary, t , can be determined by calling one of the following geometry routines:
 - PLANE1, CYLNDR, CONE, SPHERE, PLAN2P, PLAN2X, CYL2, CON2, SPH2
- Two other geometry subprograms are available to help in this task:
 - **CHGTR** for changing **USTEP** and **IRNEW** if needed
 - **FINVAL** for getting the coordinates at the end of a projected transport

Using PLANE1 and CHGTR



- Consider the two parallel planes separating three regions
- The regions are identified by the numbers 22, 23 and 24 and the planes by the numbers 6 and 7
- The *triangles* enclosing the numbers 6 and 7 have a purpose—they point in the direction of the unit normal vector and the user must define them

...PLANE1 and CHGTR (cont.)

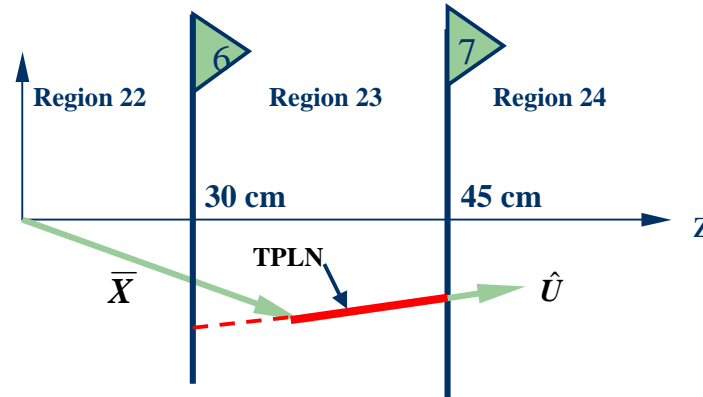


- Assume that planes 6 and 7 are located at $z = 30$ and 45 cm, respectively

$PCOORD(1, 6) = 0.0;$	$PCOORD(2, 6) = 0.0;$	$PCOORD(3, 6) = 30.0;$
$PNORM(1, 6) = 0.0;$	$PNORM(2, 6) = 0.0;$	$PNORM(3, 6) = 1.0;$
$PCOORD(1, 7) = 0.0;$	$PCOORD(2, 7) = 0.0;$	$PCOORD(3, 7) = 45.0;$
$PNORM(1, 7) = 0.0;$	$PNORM(2, 7) = 0.0;$	$PNORM(3, 7) = 1.0;$

- If particles are initially started in region 23 and discarded when they leave this region, the following **HOWFAR** will work nicely with EGS

...PLANE1 and CHGTR (cont.)



```

SUBROUTINE HOWFAR;
-----
" Two parallel planes (6,7) separating three regions (22,23,24). "
" Transport in region 23 and discard in regions 22 and 24. "
-----
COMIN/EPCONT,STACK/; "To supply IDISC and IR(NP)"

IF (IR(NP).NE.23) [ IDISC=1; "Discard particles outside region 23" ]
ELSE [ "Track particles within region 23"
CALL PLANE1(7,1,IHIT,TPLN); "Check upstream plane first"
IF (IHIT.EQ.1) [ "Surface is hit---make changes if necessary"
CALL CHGTR(TPLN,24);
]
ELSEIF (IHIT.EQ.0) [ "Heading backwards"
CALL PLANE1(6,-1,IHIT,TPLN); "To get TPLN-value (IHIT=1, a must)"
CALL CHGTR(TPLN,22); "Make changes if necessary"
]
]
RETURN;
END;

```

In the above, **SUBROUTINE CHGTR** does the following:

- If **TPLN.LE.USTEP** → **USTEP=TPLN** and **IRNEW=24** (or **22**)
- Otherwise nothing is done

Subroutine HOWFAR

\$CHGTR – The Macro Equivalent of CALL CHGTR

```
SUBROUTINE CHGTR(TVALP,IRNEWP);  
  COMIN/EPCONT/;  
  IF(TVALP.LE.USTEP) [ USTEP=TVALP; IRNEW=IRNEWP; ]  
  RETURN;  
  END;
```

-versus-

```
REPLACE {$CHGTR(,#);} WITH  
  {;IF({P1}.LE.USTEP) [USTEP={P1}; IRNEW={P2};]}
```

```
"NOTE:  EVERYWHERE $CHGTR IS USED ONE MUST  
        INCLUDE COMIN/EPCONT/"
```

- The **\$CHGTR** macro can be explained as follows:
 - The Mortran macro-processor recognizes and processes specific *strings*
 - **\$CHGTR(string1, string2)**, in its entirety, is such a string—and it also contains the substrings: *string1, string2*
 - The *string1* that is located at the position of the first # is assigned to parameter **{P1}**
 - The *string2* that is located at the position of the second # is assigned to parameter **{P2}**
 - The macro is then expanded out accordingly
- Example: **\$CHGTR(TPLN, 24);** produces

```
IF(TPLN.LE.USTEP) [USTEP=TPLN; IRNEW=24;]
```

which is equivalent to **CALL CHGTR(TPLN, 24);**

\$PLANE1 – The Macro Equivalent of CALL PLANE1

- In a very similar fashion we can create a macro called `$PLANE1` that will replace `CALL PLANE1`
- We won't go through the details here, but will simply demonstrate how both `$PLANE1` and `$CHGTR` are used in the previous example of `SUBROUTINE HOWFAR`

```
SUBROUTINE HOWFAR;  
  "-----"  
  " Two parallel planes (6,7) separating three regions (22,23,24).      "  
  " Transport in region 23 and discard in regions 22 and 24.          "  
  "-----"  
  COMIN/EPCONT,PLADTA,STACK/; "To supply many things now"  
  
  IF (IR(NP).NE.23) [ IDISC=1; "Discard particles outside region 23" ]  
  ELSE [ "Track particles within region 23"  
    $PLANE1(7,1,IHIT,TPLN); "Check upstream plane first"  
    IF (IHIT.EQ.1) [ "Surface is hit---make changes if necessary"  
      $CHGTR(TPLN,24);]  
    ELSEIF (IHIT.EQ.0) [ "Heading backwards"  
      $PLANE1(6,-1,IHIT,TPLN); "To get TPLN-value (IHIT=1, a must)"  
      $CHGTR(TPLN,22); "Make changes if necessary"  
    ]  
  ]  
  RETURN;  
  END;
```

- Note that the `COMIN` statement now contains `PLADTA` in addition to `EPCONT` and `STACK`

Subroutine HOWFAR

The **\$PLAN2P** Macro*

(* Mnemonic for *two parallel planes*)

- The **HOWFAR** example that we have been following can be simplified even further with the aid of **\$PLAN2P**

```
SUBROUTINE HOWFAR;  
  "-----"  
  " Two parallel planes (6,7) separating three regions (22,23,24).      "  
  " Transport in region 23 and discard in regions 22 and 24.          "  
  "-----"  
  COMIN/EPCONT,PLADTA,STACK/;  "To supply many things now"  
  
  IF (IR(NP).NE.23) [ IDISC=1; "Discard particles outside region 23" ]  
  ELSE [ "Track particles within region 23"  
    $PLAN2P(7,24,1,6,22,-1);  
  ]  
  RETURN;  
  END;
```

- First group of numbers (7,24,1) corresponds to checking the downstream plane and is equivalent to \$PLANE1(7,1,IHIT,TPLN) followed by \$CHGTR(TPLN,24)
- The second group (6,22,-1) corresponds to checking the upstream plane and is equivalent to \$PLANE1(6,-1,IHIT,TPLN) followed by \$CHGTR(TPLN,22)
- **\$PLAN2P** is efficient in that the second plane is only checked if necessary; namely, if the particle is really heading towards it (i.e., it makes sense to **query the downstream plane first**)

Subroutine HOWFAR

Multislab Example

- It is very simple to extend the previous HOWFAR for many slabs

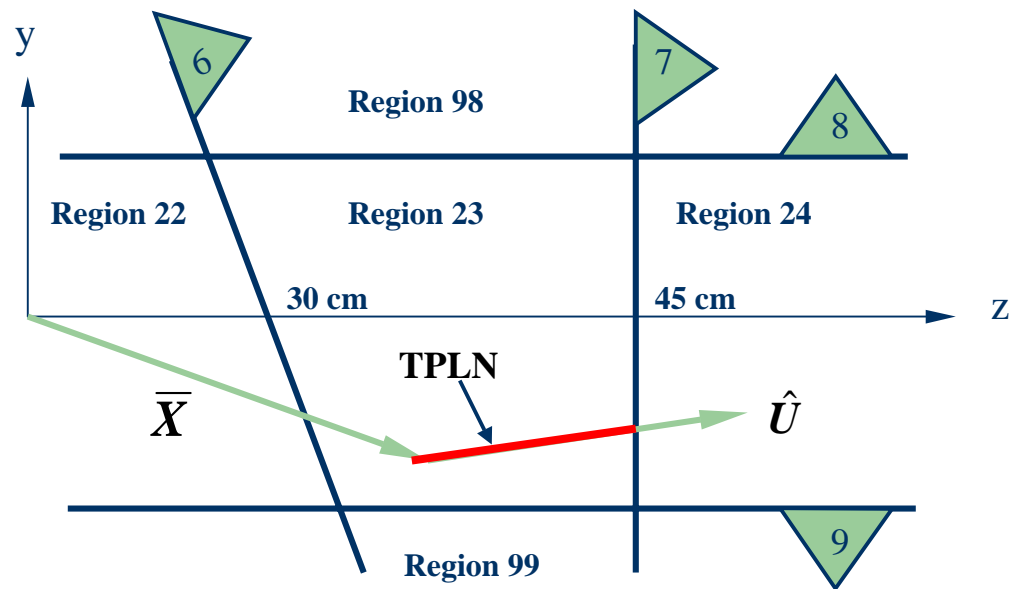
```
SUBROUTINE HOWFAR;  
  "-----"  
  " Multislab (NREG-1) shower calorimeter.          "  
  "-----"  
  COMIN/EPCONT,PLADTA,STACK/;  
  COMMON/PASSIT/NREG;                                "To make the number"  
                                                    "of regions (NREG) available"  
  
  IRL=IR(NP);                                       "Create a local variable"  
  
  IF (IRL.EQ.1.OR.IRL.EQ.NREG) [ IDISC=1;          "Upstream/downstream"  
                                "regions"  
                                ]  
  ELSE [                                           "Track particles within calorimeter proper"  
    $PLAN2P(IRL,IRL+1,1,IRL-1,IRL-1,-1);  
  ]  
  RETURN;  
  END;
```

Subroutine HOWFAR

The \$PLAN2X Macro*

(* Mnemonic for *two crossing planes*)

- Consider the geometry below consisting of five regions formed by a pair of parallel and a pair of crossing planes:



- We will impose the conditions that all particles start out in region 23, but are **discarded** when they leave it

...the following HOWFAR can be written

Subroutine HOWFAR

...\$PLAN2X Macro (cont.)

```

SUBROUTINE HOWFAR;
  "-----"
  " Two crossing planes (6,7) separating three regions "
  "   (22,23,24), with "
  " second set of parallel planes (8,9) separating three regions"
  "   (98,99)"
  "-----"
  COMIN/EPCONT,PLADTA,STACK/;

  IF (IR(NP).NE.23) [ IDISC=1; "Discard particles outside "
                      " region 23"

                    ]
  ELSE [              "Track particles within region 23"
        $PLAN2X(7,24,1,6,22,-1);
        $PLAN2P(8,98,1,9,99,1);
      ]
  RETURN;
END;

```

- It is instructive for to convince oneself that the following statements are true:
 - \$PLAN2X and \$PLAN2P must **both** be called
 - The **order** in which \$PLAN2X and \$PLAN2P are called is **not important**
 - If one has preknowledge that the radiation field moves *essentially* towards one or the other parallel plane, then \$PLAN2P can be made more efficient by **checking the preferred plane first**
 - There is **no preferred order** for checking planes with \$PLAN2X
 - USTEP and IRNEW will **always be properly selected**

Subroutine HOWFAR

The \$CYLNDR, \$CONE and \$SPHERE Macros*

- The conic surface algorithms are basically all the same and **\$CONE** and **\$SPHERE** may be used in **SUBROUTINE HOWFAR** in the same manner as **\$CYLNDR**; therefore, only **\$CYLNDR** will be described here
- We will skip the math here, but the intersection of a vector with a conic surface leads to a quadratic equation, the solutions of which are both real and imaginary and correspond to actual *physical* solutions
- The following figure shows possible trajectories intersecting a cylinder

Key:

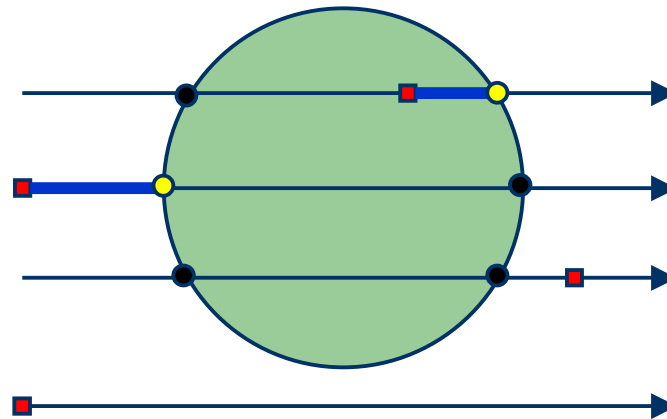
Start ■

Useful intersection ●

Useful distance —

Non-useful intersection ●

* Currently defined along the z-axis only



Subroutine HOWFAR

The \$CYLNDR Macro

- The algorithm in `$CYLNDR` was designed to take all these possibilities into account
- To accomplish the task, the user must determine whether the current particle location is *inside* or *outside* of the cylinder
- For `$CYLNDR(ICYL, INCY, IHIT, TCYL)` the parameters are explained as follows

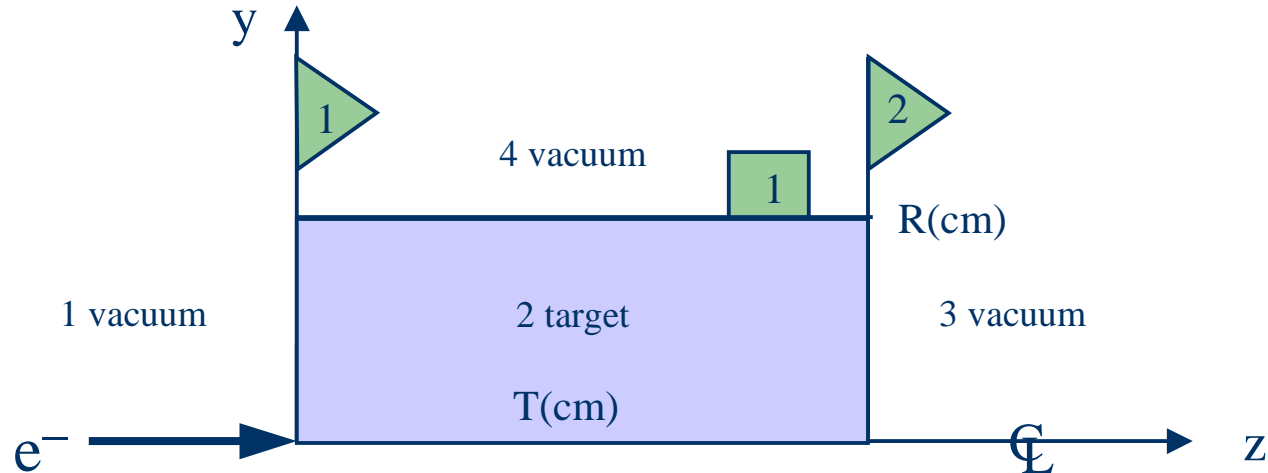
Input:	<code>ICYL</code>	Cylinder identification number
	<code>INCY = 1</code>	Current particle position is INSIDE cylinder
	<code>= 0</code>	Current particle position is OUTSIDE cylinder
Output:	<code>IHIT = 1</code>	Particle trajectory HITS surface
	<code>= 0</code>	Particle trajectory MISSES surface
	<code>TCYL</code>	Distance (shortest) to surface (when <code>IHIT=1</code>)

- `TCYL` is the *useful distance* shown by the blue line segment in the previous slide

Subroutine HOWFAR

Example: A Cylinder-Slab

- Consider a cylindrical target struck by an electron beam

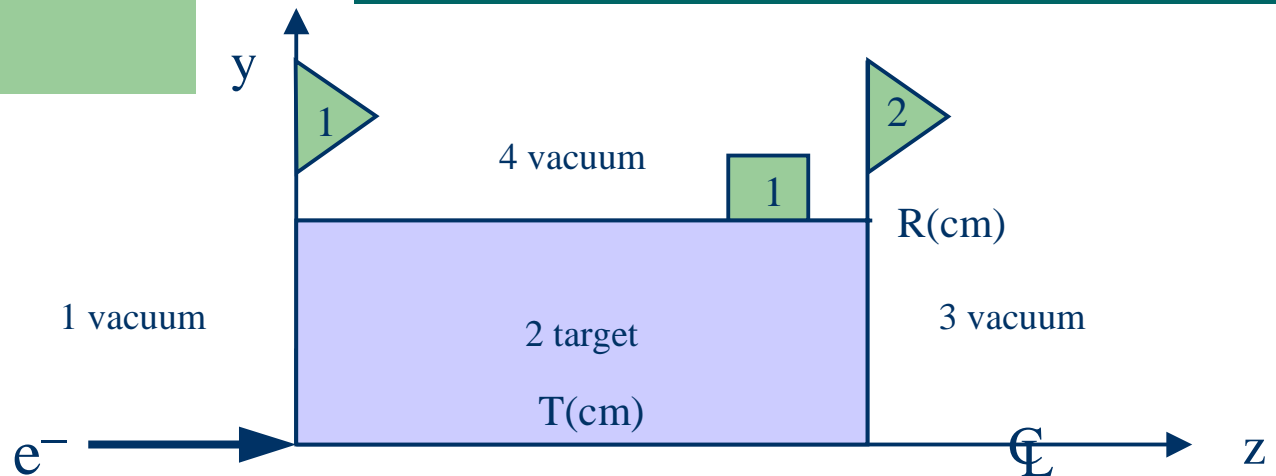


- The cylinder of rotation about the z -axis is identified by box 1 and radius R
- Planes 1 and 2 define the length of the target of thickness T
- There are four regions of interest: the target (region 2) and three vacuum regions—upstream (region 1), downstream (region 3) and surrounding the target (region 4)
- The radius (squared) of the cylinder is defined in **MAIN** and passed to **HOWFAR** via **COMIN/CYLDTA/**, and the following macro (in **egsnrc.macros**) is required

```
REPLACE { ;COMIN/CYLDTA/ ; } WITH
        { ;COMMON/CYLDTA/CYRAD2 ( $MXCYLS ) ; }
```

Subroutine HOWFAR

...Cylinder-Slab Example (cont.)



- The following will work for the above geometry:

```

SUBROUTINE HOWFAR;
"-----"
" Cylinder of rotation about the z-axis bounded by two planes.      "
"-----"
COMIN/CYLDTA,EPCONT,PLADTA,STACK;

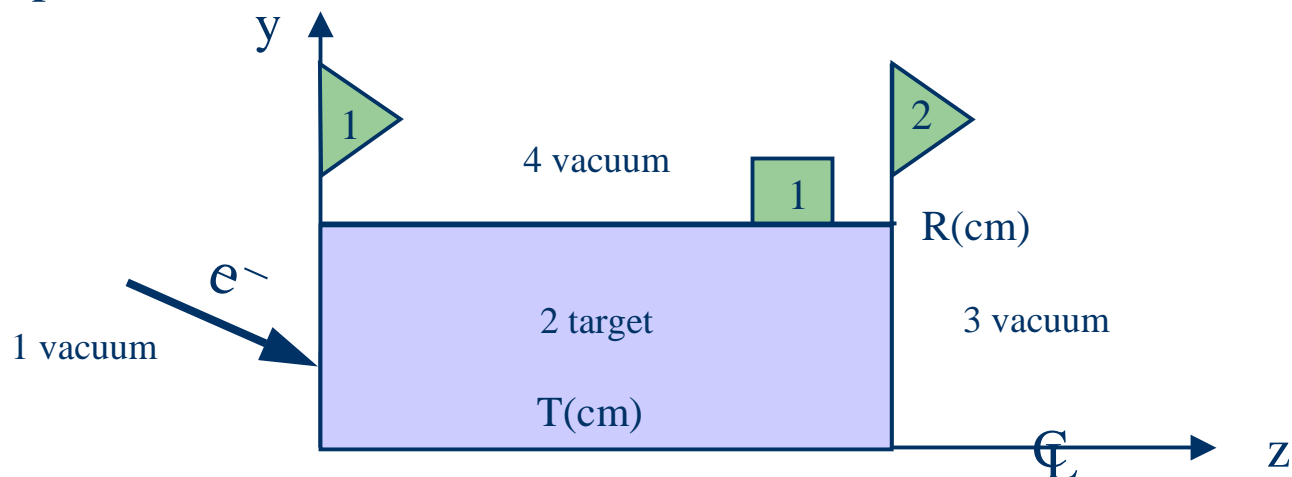
IF (IR(NP).NE.2) [ IDISC=1; "Discard particles outside the target" ]
ELSE [ "Track particles within the target"
  $CYLNDR(1,1,IHIT,TCYL); "Check the cylinder surface"
  IF (IHIT.EQ.1) [ $CHGTR(TCYL,4); "Change if necessary" ]
  $PLAN2P(2,3,1,1,1,-1); " Check the downstream plane first and"
                    " then the upstream one if necessary "
]
RETURN;
END;

```

Subroutine HOWFAR

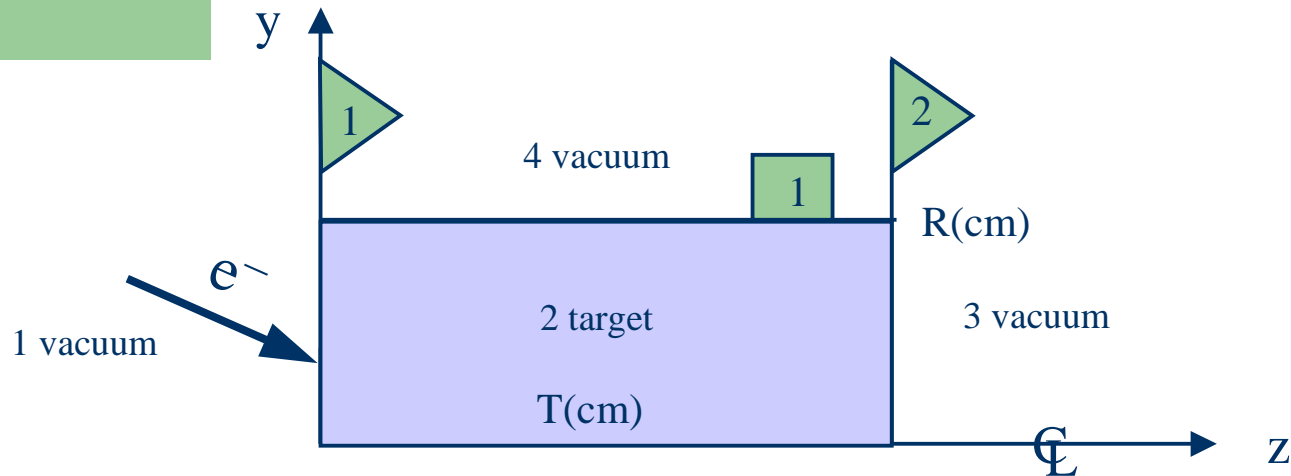
The \$FINVAL Macro

- The **\$FINVAL** macro is useful for determining the final coordinates of a particle—e.g., the coordinates at the *point of intersection* of a trajectory and a geometric surface
- To illustrate this, consider the cylinder-slab geometry of the previous example:



Assume that we have a beam to the left in region 1 and are allowing the particles to be *transported to the target*

\$FINVAL Macro (cont.)



- The following additional code could be used with our **HOWFAR** to take care of this situation

```

IF (IR(NP).EQ.1) [
    $PLANE1(1,1,IHIT,TPLN);
    IF (IHIT.EQ.1) [
        $FINVAL(TPLN,XF,YF,ZF); "Get final coordinates"
        IF ((XF*XF + YF*YF).LT.CYRAD2(1)) [ IRNXT=2; ]
        ELSE [ IRNXT=4; ]
        $CHGTR(TPLN,IRNXT);
    ]

```

Note that a square root was purposely avoided in the **IF** statement above for efficiency reasons

Subroutine HOWFAR

Closing Remarks

- A set of geometry macros is available for defining **HOWFAR**
- This lecture demonstrated how one uses these macros to create a relatively simple geometry
- But these macros (or their subroutine equivalents) can be used in a modular way to define very complex geometries
- The references at the beginning of this lecture provide more complex examples